

J1 concl.  
Sub K1 --4. (Five times amended) A device according to claim 2 wherein to said two arms are added two other movable arms so that they could overlap each other, [all] every of said movable arms being furthermore turnable around said support part into at least two directions and each of all of said arms having one substantially elastic buffer secured thereto at a distance from said support part so that the buffers of the two first arms of said four [arms] ones along said support part [ould] could have their contact faces facing the contact faces of the buffers of the two other said arms.

J2 Sub K3 --7. (Three times amended) A device according to claim 2, wherein at least one end of said support part is fitted out with a removable stop such as a clip, a rider, a pin, a key or a section of cylindrical supple sheath slipped on said support part by a gentle forcing so as to turn [those] of said two arms those which [that] are movable into removable arms.

J3 Sub n7 --9. (Five times amended) A device according to claim 2, wherein the support part has secured thereto a coupler which holds other support parts parallel to first said support part, each of said other support parts carrying at least two arms, of which [one] at least one is movable, and of which one is provided with one substantially elastic buffer.

Sub K4 --15. (Amended) A device according to claim 2, wherein the connexion between the support part and each of those of said arms which are movable along said support part is made by a loop-shaped gland [stirrup].

J4 Sub L2 --16. (Amended) The method for holding objects by clamping without any risk at all of damaging and which consists in [of] using a device including a cylindrical support part and two arms of which [one] at least one is movable along said support part, [one] at least one of said arms having a substantially elastic buffer secured thereto at a distance from the support part, said buffer having under its contact face, which is approximately at a right angle to said support part, a [so large] thickness large enough so that said buffer could act as a compression spring, said method [for holding objects by clamping without any risk at all of damaging,] comprising the steps of:

- a) applying said substantially elastic buffer against some resistant surface,
- b) exerting on the back of said arms a manual thrust,
- c) stopping this thrust so as to lock those of said arms which are movable by tilting against said support part.

Sub n13 --17. (Amended) The method according to claim 16, wherein said support part has secured thereto a coupler which supports another support part, said another support part carrying at least one movable arm, said at least one movable arm having a substantially elastic buffer secured thereto at a distance from the support part carrying said at least one movable arm, said buffer having under its contact face, which is approximately at a right angle to said support part, a [so large] thickness large enough so that said buffer could act as a compression spring, said method for holding objects by clamping without any risk at all of damaging, further comprising the steps of:

- d) applying every said substantially elastic [said] buffer against some resistant surface,
- e) exerting on the back of said arms a manual thrust,
- f) stopping this thrust so as to lock each of those movable arms by tilting against their own support part.

--18. (Amended) The method according to claim 16, wherein said support part has secured thereto a coupler which supports another support part, said another support part carrying at least one movable arm and another coupler, said at least one movable arm having a substantially elastic buffer secured thereto at a distance from the support part carrying said at least one movable arm, said buffer having under its contact face, which is approximately at a right angle to said support part, a [so large] thickness large enough so that said buffer could act as a compression spring, said method for holding objects by clamping without any risk at all of damaging, further comprising the steps of:

- d) applying every said substantially elastic [said] buffer against some resistant surface,
- e) exerting on the back of said arms a manual thrust,
- f) stopping this thrust so as to lock each of those movable arms by tilting against their own support part.

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